

TOODAY: Every statement is valid also
Metric connections (Why?) | in pseudo
riemannian
case

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$$\forall X, Y, Z \in \mathcal{X}(M)$$

$$g(X, Y) = (C'_! \circ C'_!)(g \otimes X \otimes Y)$$

$$\begin{aligned} \Rightarrow \nabla_Z(g(X, Y)) &= C'_!(C'_!(\nabla_Z g \otimes X \otimes Y + g \otimes \nabla_Z X \otimes Y + g \otimes X \otimes \nabla_Z Y)) \\ &= (\nabla_Z g)(X, Y) + g(\nabla_Z X, Y) + g(X, \nabla_Z Y) \end{aligned}$$

$$\boxed{\nabla_Z(g(X, Y)) = (\nabla_Z g)(X, Y) + g(\nabla_Z X, Y) + g(X, \nabla_Z Y)}$$

Def

$$\nabla \text{ is metric iff } \forall Z \in \mathcal{X}(M) \quad \nabla_Z g \equiv 0.$$

Thus for metric connections we have

$$\nabla_Z(g(X, Y)) = g(\nabla_Z X, Y) + g(X, \nabla_Z Y)$$

Corollary

∇ is metric $\Leftrightarrow$ Parallel transport
preserves scalar product
of vectors.

Proof

$$\gamma \mapsto Z = \frac{d\gamma}{dt}$$

Let X, Y be two vectors parallelly transported along γ , s.t.

$$X(0) = X_0, Y(0) = Y_0. \text{ We have } \frac{DX}{dt} = 0, \frac{DY}{dt} = 0$$

$$\frac{d}{dt}(g(X(t), Y(t))) = (\nabla_Z g)(X(t), Y(t)) + \cancel{g(\frac{DX}{dt}, Y)} + \cancel{g(X, \frac{DY}{dt})}$$

$$\Rightarrow : \text{ if } \nabla_Z g \equiv 0 \quad \forall Z \Rightarrow \frac{d}{dt} g(X(t), Y(t)) = 0$$

$$\Rightarrow g(X(t), Y(t)) = \text{const along } \gamma.$$

$$\Leftarrow : \text{ if } g(X(t), Y(t)) = \text{const along } \gamma \Rightarrow$$

$$\nabla_Z g \equiv 0 \text{ along } \gamma$$

but we want that $g(X(t), Y(t)) = \text{const along all } \gamma$ s

$$\Rightarrow \nabla_Z g \equiv 0 \text{ along any curve}$$

$$\Rightarrow \nabla_Z g \equiv 0 \quad \forall Z \in \mathcal{X}(M).$$

□.

This in particular means that if we calculate in local frames:

$$\nabla_\mu X_\nu = \nabla_\mu (g_{\nu\sigma} X^\sigma) = \cancel{(\nabla_\mu g)_{\nu\sigma}} X^\sigma + g_{\nu\sigma} \nabla_\mu X^\sigma$$

if connection is metric we may commute $g_{\nu\sigma}$ with ∇_μ !

But only if ∇ is metric!

Riemann tensor $\equiv (M, g)$ curvature tensor for the Levi-Civita connection.

$$\left. \begin{aligned} (Dg)_{\mu\nu} &\equiv 0 \\ \Theta^\mu &\equiv 0 \end{aligned} \right\} \Rightarrow \nabla - \text{Levi-Civita}$$

$$\Downarrow \left\{ \begin{aligned} \nabla_X g &\equiv 0 \\ \nabla_X Y - \nabla_Y X &= [X, Y] \end{aligned} \right. \quad \forall X \in \mathcal{X}(M)$$

$$\boxed{R(X, Y)Z = [\nabla_X, \nabla_Y]Z - \nabla_{[X, Y]}Z.} \quad \forall X, Y, Z \in \mathcal{X}(M)$$

↑
Riemann tensor.

Symmetries

- 1) $R(X, Y) = -R(Y, X)$
- 2) $R(X, Y)Z + R(Z, X)Y + R(Y, Z)X = 0$ 1st Bianchi
(no torsion!)
- 3) $g(R(X, Y)Z, T) = -g(R(X, Y)T, Z)$
- 4) $g(R(X, Y)Z, T) = g(R(Z, T)X, Y)$

or:

$$R(X_\mu, X_\nu)Y_\sigma = R^\tau_{\sigma\mu\nu}Y_\sigma \xleftrightarrow{g_{\mu\sigma}} R_{\sigma\mu\nu}$$

- 1) $R_{\sigma\mu\nu} = -R_{\sigma\nu\mu}$
- 2) $R_{\sigma\mu\nu} + R_{\sigma\nu\mu} + R_{\sigma\mu\nu} = 0$
- 3) $R_{\sigma\mu\nu} = -R_{\sigma\nu\mu}$
- 4) $R_{\sigma\mu\nu} = R_{\mu\nu\sigma}$

Comments

- 1) holds for any connection
- 2) holds if torsion vanishes (I^{st} Bianchi + $T \equiv 0$)
- 3) holds if connection is metric ($Dg \equiv 0$)
- 4) holds for Levi-Civita. (i.e. $T \equiv 0$ & $Dg \equiv 0$)

(homework: Thursday 23 Oct prove 3) and 4)
using any of the three languages.)

Fact # of independent components of Riemann:
 $\frac{1}{12}n^2(n^2-1)$

Thm

Riemann $\equiv 0 \iff$ there exists a local coord system (x^i) s.t.

$$g = dx^1{}^2 + \dots + dx^p{}^2 + dx^{p+1}{}^2 - \dots - dx^{n^2}{}^2$$

$$(g_{\mu\nu} = \text{diag}(1, \dots, 1, -1, \dots, -1))$$

Proof

$$\Gamma_{\mu\nu}^\alpha = \frac{1}{2} g^{\alpha\lambda} (g_{\lambda\mu,\nu} + g_{\lambda\nu,\mu} - g_{\mu\nu,\lambda}) dx^\lambda$$

$$\iff \text{Hence: } \Gamma_{\mu\nu}^\alpha \equiv 0 \Rightarrow \Omega_{\mu\nu}^\alpha = d\Gamma_{\mu\nu}^\alpha + \Gamma_{\mu\lambda}^\alpha \Gamma_{\nu}^\lambda \equiv 0 \quad \checkmark$$

$\Rightarrow R_{\mu\nu\rho\sigma}^\alpha \equiv 0$, we showed before that this means

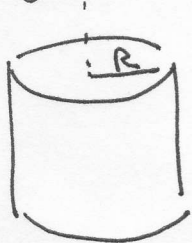
that one can make $\Gamma_{\mu\nu}^\alpha \equiv 0$ in a neighbourhood
And because $\Gamma_{\mu\nu}^\alpha \equiv 0$ this can be made in holonomic frame x^μ .
 $\Rightarrow g_{\mu\nu,\rho} = 0$ in a neighbourhood

$$\Rightarrow g_{\mu\nu} = (\text{const})_{\mu\nu}$$

$\Rightarrow$ Linear transf. of coordinates brings $g_{\mu\nu} = \text{diag}(1, -1, -1, \dots, -1)$

Example

Cylinder



$$g|_{\text{cylinder}} = dx^2 + dy^2 + dz^2 = \underset{\text{cylinder}}{\quad} \underset{\text{const}}{\quad} dz^2 + R^2 d\varphi^2$$

$$\Rightarrow R^{\mu}{}_{\nu} g_{\mu\nu} = 0 \Rightarrow \text{cylinder is } \underline{\text{flat}}.$$

Decomposition of Riemann into irreducible bitsExample

$$V = \mathbb{R}^n,$$

$$A_{\mu\nu} \in (\mathbb{R}^{n*}) \otimes (\mathbb{R}^{n*})$$

$G = GL(n, \mathbb{R})$ acts on $V^* \otimes V^*$ via:

$$V^* \otimes V^* \ni A_{\alpha\beta} \xrightarrow{a} g(\alpha)^\alpha{}_\mu g(\beta)^\beta{}_\nu A_{\alpha\beta} = A_{\mu\nu} a^{-1\alpha}{}_\mu a^{-1\beta}{}_\nu \in V^* \otimes V^*$$

Hence we have representation $g^\alpha{}_\mu g^\beta{}_\nu$ of $GL(n, \mathbb{R})$ in $V^* \otimes V^*$.

But this representation is reducible. Indeed

$V^* \wedge V^*$ and $V^* \odot V^*$ are $GL(n, \mathbb{R})$ invariant subspaces.

$$A_{\alpha\beta} = A_{(\alpha\beta)} + A_{[\alpha\beta]}$$

$$A_{(\alpha\beta)} = \frac{1}{2} (A_{\alpha\beta} + A_{\beta\alpha}) \in V^* \odot V^*$$

$$A_{[\alpha\beta]} = \frac{1}{2} (A_{\alpha\beta} - A_{\beta\alpha}) \in V^* \wedge V^*$$

$$V^* \otimes V^* = V^* \odot V^* \oplus V^* \wedge V^*$$

$\nwarrow \quad \nearrow \quad \pm 1$ eigenspaces of S s.t.

$$S A_{\alpha\beta} = A_{\beta\alpha}.$$

$g(a)^{\alpha\beta} \vee A_{(\alpha\beta)} = A'_{\mu\nu}$ is symmetric!

$g(a)^{\alpha\beta} \vee A_{[\alpha\beta]} = A'_{\mu\nu}$ is antisymmetric!

This is the end! Spaces $V^* \otimes V^*$ and $V^* \wedge V^*$ are irreducible w.r.t. $GL(n, \mathbb{R})$.

Suppose now that we in addition have (pseudo)riemannian metric $g_{\mu\nu}$ in $V = \mathbb{R}^n$.

We restrict the group $GL(n, \mathbb{R})$ to its subgroup $O(g)$ preserving metric:

$$O(g) = \{ a \in GL(n, \mathbb{R}) \text{ s.t. } g_{\mu\nu} \tilde{a}^{\mu\alpha} \alpha \tilde{a}^{\beta\nu} = g_{\alpha\beta} \}.$$

What about decomposition of $V^* \otimes V^*$ on irreducibles w.r.t. the restricted group $O(g)$?

We have

$$V^* \otimes V^* \underset{\substack{\uparrow \\ O(g)}}{=} V^* \wedge V^* \oplus \underbrace{V^* \odot V^*}_{\substack{\uparrow \\ \text{but now this is reducible!}}}$$

It has an invariant subspace

$$Tr = \{ A_{\mu\nu} = \lambda g_{\mu\nu}, \lambda \in \mathbb{R} \} \subset V^* \odot V^*$$

$$V^* \odot V^* = (V^* \odot V^*)_0 \oplus Tr(V^* \odot V^*)$$

We have $A_{\mu\nu}$, $g_{\mu\nu}$ and its inverse $g^{\alpha\beta}$ s.t.

7

$$g_{\alpha\beta} g^{\beta\gamma} = \delta_{\alpha}^{\gamma}.$$

$$A_{(\mu\nu)} \rightsquigarrow A = g^{\mu\nu} A_{\mu\nu}$$

$$A_{(\mu\nu)} \rightsquigarrow \check{A}_{(\mu\nu)} = A_{(\mu\nu)} - \frac{1}{n} A g_{\mu\nu}$$

is traceless.

$$\boxed{A_{\mu\nu} = \underbrace{A_{[\mu\nu]}}_{V^{\alpha} \wedge V^{\beta}} + \underbrace{\check{A}_{(\mu\nu)}}_{(V^{\alpha} \otimes V^{\beta})} + \frac{1}{n} \underbrace{A g_{\mu\nu}}_{\text{Tr}(V^{\alpha} \otimes V^{\beta})}$$

With the exception of $\dim V = 4$ (+orientability) this is decomposition into irreducibles w.r.t. $O(q)$.

The same for Riemann:

$$R^{\mu}{}_{\nu\sigma\tau} \rightsquigarrow R_{\nu\sigma} = R^{\mu}{}_{\nu\mu\sigma} \quad \left\| \begin{array}{l} \text{This is called} \\ \text{RICCI tensor} \end{array} \right.$$

$\uparrow$
is symmetric

$$R_{\nu\sigma} \xrightarrow{\text{Tr}} R = g^{\nu\sigma} R_{\nu\sigma} \quad \left\| \begin{array}{l} \text{This is called / SCALAR} \\ \text{RICCI scalar / CURVATURE} \end{array} \right.$$

$$\check{R}_{\nu\sigma} = R_{\nu\sigma} - \frac{1}{n} R g_{\nu\sigma}$$

$$R^{\mu\nu}{}_{\sigma\tau} = \boxed{C^{\mu\nu}{}_{\sigma\tau}} + a \delta_{[\sigma}^{\mu} \check{R}_{\tau]}^{\nu]} + b \delta_{[\sigma}^{\mu} \delta_{\tau]}^{\nu]} R$$

totally traceless.

Calculate a and b .

1) contraction over μ, σ :

$$R^\nu_\sigma = \frac{a}{4} (n \check{R}^\nu_\sigma - \check{R}^\nu_\sigma - \check{R}^\nu_\sigma + \cancel{\delta^\nu_\sigma R}) + \frac{b}{2} (n-1) \delta^\nu_\sigma R$$

but always:

$$R^\nu_\sigma = \check{R}^\nu_\sigma + \frac{1}{n} \delta^\nu_\sigma R$$

hence:

$$\frac{a}{4} (n-2) = 1 \Rightarrow a = \frac{4}{n-2}$$

$$\frac{b}{2} (n-1) = \frac{1}{n} \Rightarrow b = \frac{-2}{n(n-1)}$$

$$R^{\mu\nu} g_{\sigma\sigma} = C^{\mu\nu}{}_{\sigma\sigma} + \frac{4}{n-2} \delta^\mu_\sigma \check{R}^{\nu\sigma} + \frac{2}{n(n-1)} \delta^\mu_\sigma \delta^{\nu\sigma} R$$

Weyl tensor.

Low dimensions

$$n=1 \Rightarrow R_{\mu\nu\rho\sigma} \equiv 0$$

$$n=2 \Rightarrow R_{\mu\nu\rho\sigma} \text{ has only one component}$$

$$\Rightarrow C_{\mu\nu\rho\sigma} \equiv 0, \check{R}_{\mu\nu} \equiv 0 \Rightarrow \text{only } R \neq 0.$$

$$n=3 \Rightarrow \text{six components} \Rightarrow C_{\mu\nu\rho\sigma} \equiv 0. \text{ All curvature in } R_{\mu\nu}$$

$$n \geq 4 \text{ in general } C_{\mu\nu\rho\sigma} \neq 0.$$

$$\frac{1}{12} n^2 (n^2 - 1) \begin{matrix} \nearrow n=1 \rightarrow 0 \\ \nearrow n=2 \rightarrow 1 \\ \rightarrow n=3 \rightarrow 6 \\ \searrow n=4 \rightarrow 20 \end{matrix}$$

Def

Two metrics g and $\hat{g}$ are conformally equivalent
iff there exists $\tau: M \rightarrow \mathbb{R}$ s.t.

$$\hat{g} = e^{2\tau} g.$$

Thm

- 1) $\hat{C}^{\mu}_{\nu\sigma} = C^{\mu}_{\nu\sigma}$ for conformally equivalent metrics.
- 2) $n \geq 4$ a metric g is conformally equivalent to a flat metric iff $C^{\mu}_{\nu\sigma} \equiv 0$.

Analogous fact for Riemann:

- 2) $R^{\mu}_{\nu\sigma} \equiv 0 \iff$ metric g is isometric to flat metric

$$\left\{ \begin{array}{l} \text{Isometry} \\ (M, g) \xrightarrow{\varphi} (M', g') \\ \varphi^* g' = g \end{array} \right.$$

$$1) \quad \varphi^* R' = R$$